

# Weighted Energy Dissipation method for gradient flows - Savaré. lecture 1.

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Gradient flows  $X$  ambient space,  $\varphi: X \rightarrow (-\infty, +\infty]$  functional.

In specific example:  $X = \mathbb{R}^n$ ,  $\varphi \in C^1$ , then G.F. is subviny.

$$\begin{cases} \dot{u}(t) + D\varphi(u(t)) = 0 \\ u(0) = u_0 \end{cases}$$

$X = H$ , Hilbert space,  $\varphi$  is convex (or  $\lambda$ -convex) + lower s.c.

$D\varphi \rightsquigarrow \partial\varphi$  (multi-valued, sub differential).

$$\begin{cases} \dot{u}(t) + \partial\varphi(u(t)) \ni 0 \\ u(0) = u_0 \end{cases}$$

Bugis, Curchell, Kenen, Poggi. '70.

$X = B$  space,  $\varphi$  is convex +  $C^1$ ,  $\varphi$  is diff of convex functions } requires refined techniques

$X =$  metric space.

De Giorgi, Marino, Socolon, Tosques, De Giorgi ~ '90.

Ambrosio-Gigli-S.

Banach spaces  $\partial\varphi(u(t)) \in X'$  (dual  $\rightarrow$  in finite dim or Hilbert, identify  $X'$  with  $H$ ).

dual inclusion.  $\frac{1}{2}\|\dot{u}\|_{X'}^2$ . (Celli; Visintin, Celli).

$(X, d)$  complete metric space,  $\varphi: X \rightarrow (-\infty, +\infty]$  l.s.c.

In smooth situation,

$$\begin{aligned} \dot{u}(t) + D\varphi(u(t)) = 0 &\Leftrightarrow \frac{d}{dt} \varphi(u(t)) = -|\dot{u}(t)|^2 = -|D\varphi(u(t))|^2 \\ \text{vector eq.} &\Leftrightarrow \frac{d}{dt} \varphi(u(t)) + \frac{1}{2} (|\dot{u}(t)|^2 + |D\varphi(u(t))|^2) \leq 0 \\ &\text{Scalar eq.} \end{aligned}$$

Chain rule:

$$\frac{d}{dt} \varphi(u(t)) = \langle D\varphi(u(t)), \dot{u}(t) \rangle = -|\dot{u}(t)|^2 = -|D\varphi(u(t))|^2.$$

or by C.S. inequality as above!  
integration.

$$\Leftrightarrow \varphi(u(t)) + \frac{1}{2} \int_0^t (|\dot{u}(v)|^2 + |D\varphi(u(v))|^2) dv \leq \varphi(u_0) \quad \forall t \geq 0.$$

Note, in B-space,

$\langle D\varphi(u(t)), \dot{u}(t) \rangle$  is duality,  $X^* \times X$ ,

$$\text{so, } \langle D\varphi(u(t)), \dot{u}(t) \rangle = -\|\dot{u}(t)\|_X = -\|D\varphi(u(t))\|_{X^*}.$$

Back to  $(X, d)$  metric space:

$u: I \rightarrow X$  in  $AC^p$  ( $u \in AC^p(I, X)$ ). if  $\exists v \in L^p(I)$ ,  $v \geq 0$ .

$$d(u(s), u(t)) \leq \int_s^t v(v) dv \quad s, t \in I, s < t. \quad (*)$$

$p \in [1, \infty]$ . - Yes,  $p = \infty$  is ok,  $AC = AC^1$ .

If  $u \in AC(I, X)$ , then for almost every  $t \in I$ , then theorem.

$$\exists \lim_{h \rightarrow 0} \frac{d(u(t), u(t+h))}{|h|} =: |\dot{u}(t)|$$

↑ Borel function.

$\|u\| \leq v \Rightarrow \|u\| \in L^1$  and  $\|u\|$  is the minimal v. Schöpfung (\*)

If  $X$  is Hilbert or Banach reflexive,

$$\Rightarrow u \in AC(I, X)$$

$\Rightarrow u$  is w.e. differentiable and

$$\exists \dot{u}(t) = \lim_{h \rightarrow 0} \frac{u(t+h) - u(t)}{h}$$

$$\bullet \|\dot{u}(t)\| = \|\dot{u}(t)\|_X$$

$$\bullet u(t) = u(s) + \int_s^t \dot{u}(\tau) d\tau$$

### Upper gradient and slope

$G: X \rightarrow [0, \infty]$  is an upper gradient for  $\varphi$  if for every  $u \in AC([0, 1], X)$  it

$$(UG1) \int_0^1 G(u(t)) |\dot{u}(t)| dt < +\infty$$

$$\text{then } (UG2) |\varphi(u(1)) - \varphi(u(0))| \leq \int_0^1 G(u(t)) |\dot{u}(t)| dt$$

• Now, in  $\mathcal{B}$ -space.

$$\left| \frac{d}{dt} \varphi(u(t)) \right| = |\langle D\varphi(u(t)), \dot{u}(t) \rangle| \leq \|D\varphi(u(t))\| \|\dot{u}(t)\|$$

In this situation, replace  $D\varphi$  by  $G$ .

$$\bullet \text{Upper Grad. implies } (UG1) \Rightarrow \left| \frac{d}{dt} \varphi(u(t)) \right| \leq G(u(t)) \cdot |\dot{u}(t)| \text{ a.e. } (UG3)$$

• Candidate for upper G: slope (descending).

$$|D\varphi|(u) := \limsup_{v \rightarrow u} \frac{(\varphi(u) - \varphi(v))_+}{d(u, v)}$$

$(x)_+ = \text{positive part of } x$ .

Remark. If  $\varphi(u(t))$  differentiable at  $t$ , then

$$\left| \frac{d}{dt} \varphi(u(t)) \right| \leq |\partial \varphi|(u(t)) |\dot{u}|(t).$$

$\exists$  i.e., slope is always a candidate "upper gradient" (UG).

However, you don't always get (UG2).

When  $|\partial \varphi|$  is an upper gradient, then

$$|\varphi(u(t)) - \varphi(u(s))| \leq \int_s^t |\partial \varphi|(u(r)) |\dot{u}|(r) dr.$$

Let  $(X, d)$  be a complete metric space,  $\varphi: X \rightarrow (-\infty, +\infty]$  be a l.s.c. functional,  $G: X \rightarrow [0, +\infty]$  an upper gradient.

Given  $u_0 \in X$ , a curve  $u: [0, +\infty) \rightarrow X$  is a G.F.

of  $\varphi$  starting from  $u_0$  if  $u \in AC_{loc}^2([0, +\infty); X)$  and

$$\varphi(u(t)) + \frac{1}{2} \int_0^t (|\dot{u}|^2(r) + G^2(u(r))) dr \leq \varphi(u_0) \quad \forall t \geq 0.$$

$$\mathcal{D}(\varphi) = \{u \in X : \varphi(u) < +\infty\}.$$

• From the def<sup>n</sup> and the BG property,

$$\forall u \in AC_{loc}([0, +\infty]) \text{ and}$$

$$\frac{d}{dt} \varphi(u(t)) = -|\dot{u}|^2(t) = -G^2(u(t)) \quad \text{t-a.e.}$$

• Assume that:  $\exists \varphi(u) \geq -a - b d(u, u_*)$ . for some  $a, b \geq 0, u_* \in X$ .

$\#$  If  $(u_n) \in X$ ;  $d(u_n, u_m) \leq C$ ,  $\varphi(u_n) \leq C$ .  $\forall n, m \in \mathbb{N}$ .

$$\Rightarrow \exists u_n \rightarrow u.$$

(II) ~~is~~  $G (\leq |\partial \varphi|)$  is lower semicontinuous.

(4)

Then (I)-(III)

$\Rightarrow \bar{u} \in \mathcal{D}(\varphi)$ ,  $\exists u \in AC_{loc}^2([0, +\infty), X)$  a G.F.  
for  $\varphi$  station at  $\bar{u}$ .

Variational WED formulation:

$\varepsilon > 0$ ,  $\mu_\varepsilon = \frac{e^{-t/\varepsilon}}{\varepsilon} \mathcal{L}^1$ , probability measure on  $[0, +\infty)$ .

$$I_\varepsilon(u) := \int_0^{+\infty} \left( \frac{\varepsilon}{2} |u'|^2(t) + \varphi(u(t)) \right) d\mu_\varepsilon(t).$$

$$= \int_0^{+\infty} e^{-t/\varepsilon} \left( \frac{1}{2} |u'|^2(t) + \frac{1}{\varepsilon} \varphi(u(t)) \right) dt, \quad u \in AC_{loc}^2([0, +\infty), X)$$

• let  $u_\varepsilon$  be a minimiser of  $I_\varepsilon$  among all curves in  $AC_{loc}^2([0, +\infty), X)$  with  $u(0) = \bar{u}$ . ( $u_\varepsilon$  exists assum (I) & (II))

•  $\exists \varepsilon_n \downarrow 0$ ,  $u_{\varepsilon_n}(t) \rightarrow u(t)$ ,  $\forall t$ .

•  $u$  is a gradient flow for  $\varphi$  (and  $G$ ) (you need 3)  
level  $\nearrow$  semi-continuity of  $G$ .

History:

$\varphi$ : quadratic,  $X$  = Hilbert  $\rightarrow$  Lions-Magenes.

Ilmanen '94, De Giorgi '96. (Minimal surfaces).

Milnor, Ortiz, Stefanelli - Hilbert case,  $\varphi$  convex.

Smooth (finite dim case):  $u_\varepsilon$  is a minimiser.

$$\Rightarrow -\varepsilon u_\varepsilon''(t) + u_\varepsilon'(t) + \mathbb{D}\varphi(u_\varepsilon(t)) = 0. \quad (**)$$

gradient perturbed by 2nd order term.

(5)

(\*) This is a elliptic problem, because we have  $-\varepsilon u''(t)$ , ie, sign is -ve.

Fix  $v \in C_c^\infty([0, \infty); \mathbb{R}^d)$ ,  $u + \delta v$ ,  $\delta$  small.

$I_\varepsilon(u + \delta v) \geq I_\varepsilon(u)$ , ie check.

$$\frac{d}{d\delta} \int_0^{+\infty} \left( \frac{\varepsilon}{2} |u_\varepsilon + \delta v|^2 + \psi(u_\varepsilon + \delta v) \right) dy_\varepsilon \Big|_{\delta=0}$$

$$\Rightarrow \int_0^{+\infty} \varepsilon \langle u_\varepsilon'(t), v(t) \rangle + \langle D\psi(u_\varepsilon(t)), v(t) \rangle dy_\varepsilon$$

$\forall v \in C_c^\infty([0, \infty), \mathbb{R}^d)$

Integration by parts:  $\int_0^{+\infty} \varepsilon \langle w(t), v(t) \rangle dy_\varepsilon = \int_0^{+\infty} (-\varepsilon w'(t) + w(t), v(t)) dy_\varepsilon$

$+ \varepsilon \langle w(0), v(0) \rangle$   
~~if not 0~~  
 Some  $\neq 0 \in \text{supp } w$  in gen.

So,  $\int_0^{+\infty} \langle -\varepsilon (u_\varepsilon'' + u_\varepsilon' + D\psi(u)_v(t)) \cdot dy_\varepsilon(t) = 0$

comes from setting  $w = u_\varepsilon$

Why gen approximation?

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$D\psi$  keeps up:

Marginal functionals,  $X = \text{top / bottom}$ , not convex or  $\Gamma$  convex

$\varphi(u) = \min \Phi(u, X)$ ,  $X \in Y \leftarrow$  some space  $Y$ ,  $\Phi$  nice func.

$\varphi = H^{-1}(\varrho)$ ,  $\chi \in H^1(\varrho)$ ,  $\Phi(u, X) = \int_\Omega f(u(x)) dx + \frac{1}{2} \int |u - \chi|^2 dx + \frac{1}{2} \int |\chi|^2 dx$

Underlying diff.  $\partial \varphi(u) = -\Delta(u - \chi)$ , where  $\chi$  solves  $-\Delta \chi + \chi = u$  < more than one sol<sup>n</sup>.

Cub diff multi-valued.  $\varphi \leftarrow \chi$  (6)

~~However~~

The equation to solve is

$$\begin{cases} \partial_x \psi - \Delta(\psi - \varphi) = 0 \\ -\Delta \varphi + W'(\varphi) + \varphi = \mu \end{cases}$$

So, Slope is not good, because if we take  $\mu_2$  minimum, it may flip b/w solns to b/c  $\varphi$  is multi-valued.

~~Algorithm~~  $G, F: \quad \varphi(\mu) = \inf_x (E(\mu) + \mu X + G(X)).$   
 $= E(\mu) - G^*(\mu).$

and  $\begin{cases} \partial_x \mu + DE(\mu) = X \\ DG(X) = \mu \end{cases}$

~~Then we proceed via G-F machinery.  
 Then this choice of  $G$  is the "right"  $G$ , if it chooses minimum of the  $X$ 's.~~

$$\partial_x \mu + DE(\mu) + \underbrace{(DG)^*(\mu)} = 0$$

If next  $G, F$ , is convex then this is multi-valued, which is the problem in prev. example.

